

An analytical placement tool for the Coriolis toolchain

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The Coriolis toolchain

Introduction to placement of VLSI circuits

Coloquinte: design choices

Improved legalization

Scheduling for detailed placement

Results

The Coriolis toolchain

Introduction to placement of VLSI circuits

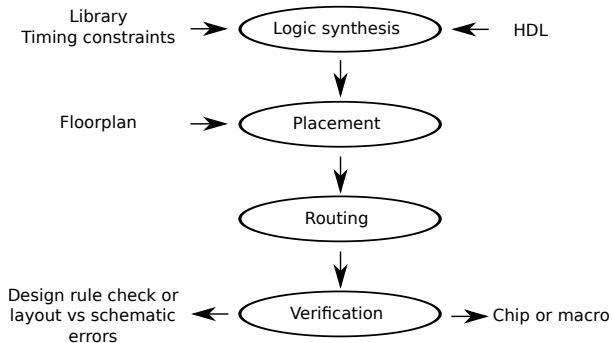
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The digital synthesis flow



Remember Alliance?

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An complete, open toolchain developped in the lab

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An complete, open toolchain developped in the lab
Coriolis: Physical design only

Hurricane: a powerful database

Hurricane: a powerful database

- ▶ Hierarchical

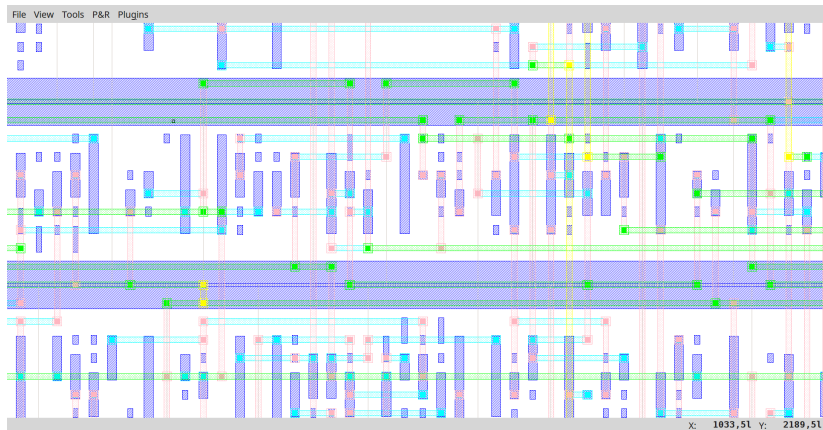
Hurricane: a powerful database

- ▶ Hierarchical
- ▶ Powerful access methods

Hurricane: a powerful database

- ▶ Hierarchical
- ▶ Powerful access methods
- ▶ Frontends/Backends

Kite: an efficient router



The Coriolis toolchain

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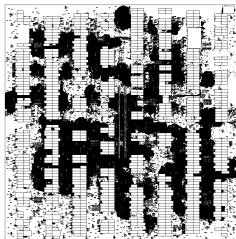
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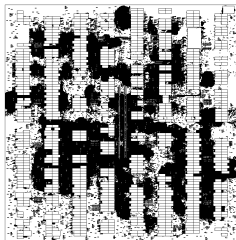
Scheduling for detailed placement

Results

The need for placement tools



The need for placement tools



- ▶ Several thousands – millions – of cells
- ▶ Partly determines the circuit's quality

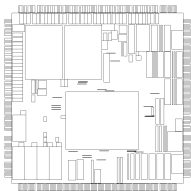
What is a good placer?

- ▶ Various optimization objectives
 - ▶ Wirelength
 - ▶ Routability
 - ▶ Timing
- ▶ Lots of open benchmarks [3]

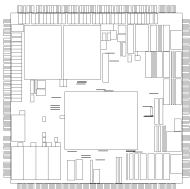
What is a good placer?

- ▶ Various optimization objectives
 - ▶ Wirelength
 - ▶ Routability
 - ▶ Timing
- ▶ Lots of open benchmarks [3]
- ▶ In practice, we want everything:
 - ▶ Error-free routing
 - ▶ Fast placement
 - ▶ Fast and low-power circuit

Two types of placement problems

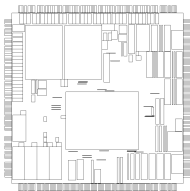


Two types of placement problems



- ▶ Big modules → Floorplanning
 - ▶ Irregular rectangles
 - ▶ Few modules

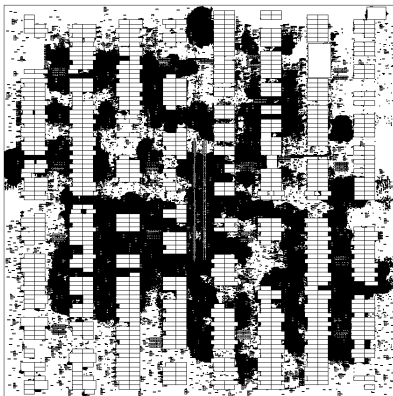
Two types of placement problems



- ▶ Big modules → Floorplanning
 - ▶ Irregular rectangles
 - ▶ Few modules

- ▶ Standard cell placement
 - ▶ Uniform height ⇒ placed in rows
 - ▶ 10^6 cells or more

The real worlds: mixed-size placement



In practice, circuits have both macros and standard cells

Before the technical stuff...

Obviously....

Before the technical stuff...

Obviously.... It is NP-complete.

Before the technical stuff...

Obviously.... It is NP-complete.

- ▶ Bin-packing
- ▶ Multiple-machine scheduling
- ▶ Graph partitioning
- ▶ Steiner trees

Algorithms

Simulated annealing and metaheuristics

Simulated annealing

- ▶ Accepts bad moves depending on a temperature
- ▶ *Theoretically* converges

Simulated annealing and metaheuristics

Simulated annealing

- ▶ Accepts bad moves depending on a temperature
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- ▶ But not in *reasonable* time

Simulated annealing and metaheuristics

Simulated annealing

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Made it quite far thanks to Timberwolf [6]

Three-step placement

Use multiple steps to obtain a good placement

Three-step placement

Use multiple steps to obtain a good placement

- ▶ A global placement step
 - ▶ Approximate positions
 - ▶ Overlaps are possible
 - ▶ Only density constraints

Three-step placement

Use multiple steps to obtain a good placement

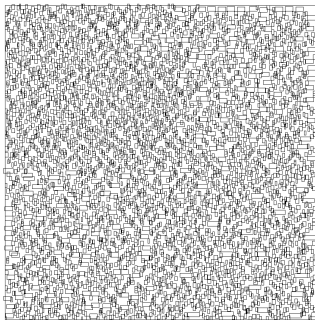
- ▶ A global placement step
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- ▶ A legalization step
 - ▶ Obtain an overlap-free placement

Three-step placement

Use multiple steps to obtain a good placement

- ▶ A global placement step
 - ▶ Approximate positions
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 - ▶ Only density constraints
- ▶ A legalization step
 - ▶ Obtain an overlap-free placement
- ▶ A detailed placement step
 - ▶ Remove local suboptimalities

Visually



Global placement result



Final placement

Global placement is everything

Global placement is the *most performance-critical* part

Global placement is everything

Global placement is the *most performance-critical* part

- ▶ There is only so much you can do with detailed placement

Detailed placement is limited

Legalization

Detailed placement is limited

Legalization

- ▶ Simple algorithms
- ▶ Needs to succeed, but not critical for quality

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Detailed placement

- ▶ Simple concepts
 - ▶ Swaps
 - ▶ Reordering
 - ▶ Moves

Detailed placement is limited

Legalization

- ▶ Simple algorithms
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Detailed placement

- ▶ Simple concepts
 - ▶ Swaps
 - ▶ Reordering
 - ▶ Moves
- ▶ Small search space

Global placement algorithms

Two approaches:

Global placement algorithms

Two approaches:

- ▶ Discrete view: the circuit is a graph
⇒ Partitioning

Global placement algorithms

Two approaches:

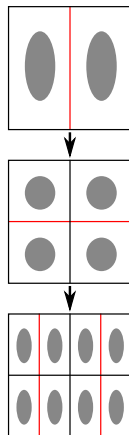
- ▶ Discrete view: the circuit is a graph
⇒ Partitioning
- ▶ Continuous view: it is a vector of positions
⇒ Analytical placement

Partitioning placers

Basic idea

- ▶ Partition the circuit
- ▶ Cut as few wires as possible
- ▶ Allocate the parts to placement regions

Some nice achievements with
Capo [5]



Lots of variations and improvements

- ▶ Partitioning algorithm (Fiduccia-Mattheyses)
- ▶ Cut costs and fixed terminals
- ▶ Free-space handling

Analytical placers

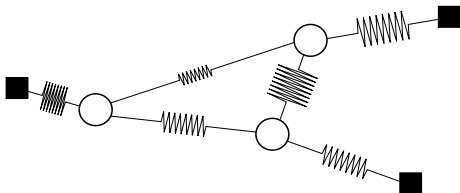
Basic idea

- ▶ A convex cost function
- ▶ A *huge* vector of positions
- ▶ Optimize

Most current placers [3]

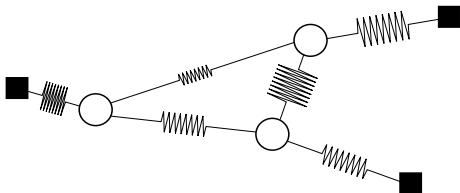
Optimization methods: quadratic placers

Model wires as springs [1]



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Easy to solve: sparse symmetric linear system

Optimization methods: nonlinear placers

Closer model of the cost function

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Closer model of the cost function

Only first-order methods:

- ▶ Conjugate gradient
 - ▶ Needs line-search
 - ▶ Slower than the linear one

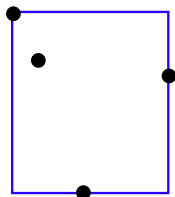
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Closer model of the cost function

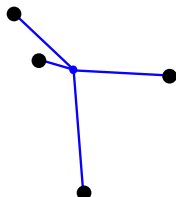
Only first-order methods:

- ▶ Conjugate gradient
 - ▶ Needs line-search
 - ▶ Slower than the linear one
- ▶ Nesterov
 - ▶ Constant steps
 - ▶ Recent comeback of nonlinear methods [3]

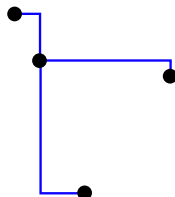
Usual cost functions



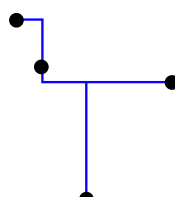
HPWL



star



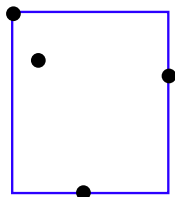
RMST



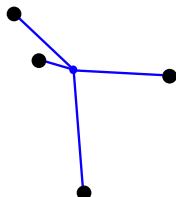
RST

Wirelength models

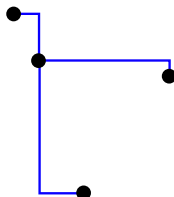
Usual cost functions



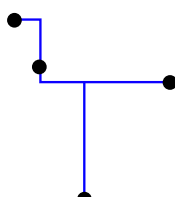
HPWL



star



RMST



RST

Wirelength models

$$HPWL = \sum_{c \in \{x,y\}} \sum_{n \in nets} (\max_{pin \in n} c_{pin} - \min_{pin \in n} c_{pin})$$

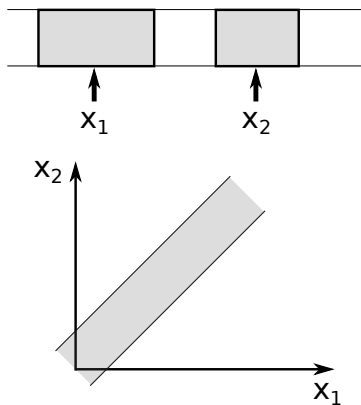
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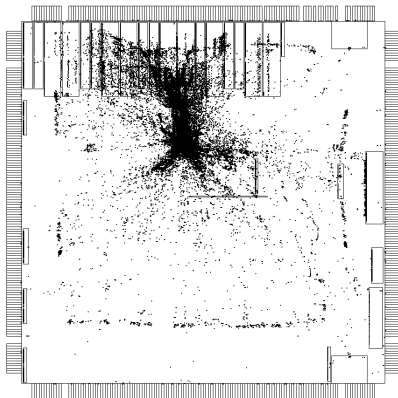
Non-convex solution space!

Beware!

Non-convex solution space!



Problem



Lots of overlaps

Handling density constraints

Handling density constraints

Back to partitioning

Handling density constraints

Back to partitioning \Leftarrow based on the positions

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Force-directed placers \Leftarrow add a penalty function

Handling density constraints

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- ▶ Local penalty

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- ▶ Global potential

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Force-directed placers \Leftarrow add a penalty function

- ▶ Local penalty
- ▶ Global potential
- ▶ "Projection" on the solution space

Handling density constraints

Back to partitioning \Leftarrow based on the positions

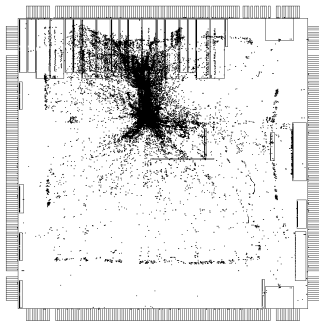
Force-directed placers \Leftarrow add a penalty function

- ▶ Local penalty
- ▶ Global potential
- ▶ "Projection" on the solution space

Repeat

Obtaining a feasible solution: lookahead legalization

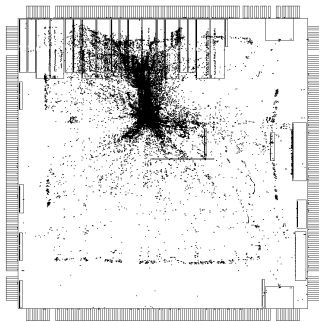
Remove density overflow, minimize the displacement



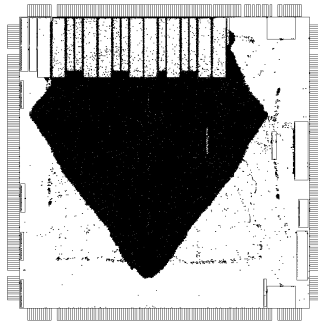
Optimization result

Obtaining a feasible solution: lookahead legalization

Remove density overflow, minimize the displacement



Optimization result



Projection

Lots of variations and improvements

- ▶ Penalty function
- ▶ Cost function
- ▶ Legalization algorithm

Lots of variations and improvements

- ▶ Penalty function
- ▶ Cost function
- ▶ Legalization algorithm
- ▶ Additional refinements

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Benchmark winners

The best placers are analytical. No other rule

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Placer	Optimization	Density handling	Refinement
ePlace	Nonlinear	FD (potential)	No
Maple	Quadratic	FD (legalizing)	Yes
Polar	Quadratic	FD (legalizing)	Yes
BonnPlace	Quadratic	Partitioning	No?

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- ▶ Rather force-directed

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- ▶ Rather force-directed
- ▶ + various algorithms

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- ▶ Rather force-directed
- ▶ + various algorithms
- ▶ + **trial-and-error**

Coloquinte is a force-directed quadratic placer

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- ▶ Lookahead legalization \Rightarrow Local density control

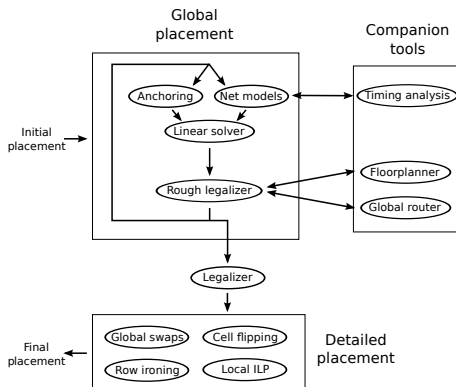
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- ▶ Analytical \Rightarrow Flexible cost function
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- ▶ Force-directed \Rightarrow best results
- ▶ Lookahead legalization \Rightarrow Local density control
- ▶ **But**

Coloquinte is a force-directed quadratic placer

- ▶ Analytical \Rightarrow Flexible cost function
- ▶ Quadratic \Rightarrow best results (until recently)
- ▶ Force-directed \Rightarrow best results
- ▶ Lookahead legalization \Rightarrow Local density control
- ▶ **But** no refinement

Coloquinte's structure



What is new in Coloquinte?

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- ▶ Focus on good lookahead legalization

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- ▶ Penalty scheduling

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- ▶ Focus on good lookahead legalization
- ▶ Algorithms for detailed placement
- ▶ Penalty scheduling
- ▶ Net models

The need for extensive benchmarking

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Small change \Rightarrow random quality variations

The need for extensive benchmarking

Small change \Rightarrow random quality variations

Experienced with:

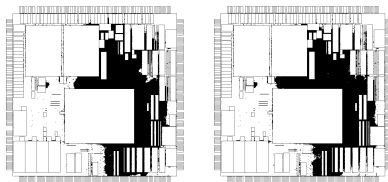
- ▶ Penalty type
- ▶ Penalty weight

The need for extensive benchmarking

Bigblue1: WL +0.8%



Adaptec2: WL -2.1%



A simple change: linear vs quadratic penalty

Can we suppress these variations?

Can we suppress these variations?

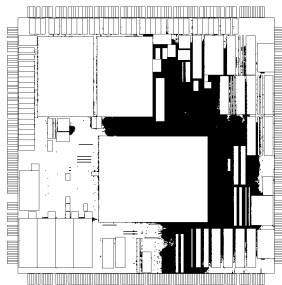
No!

Can we suppress these variations?

No!

Definitely not

⇒ measure again and again



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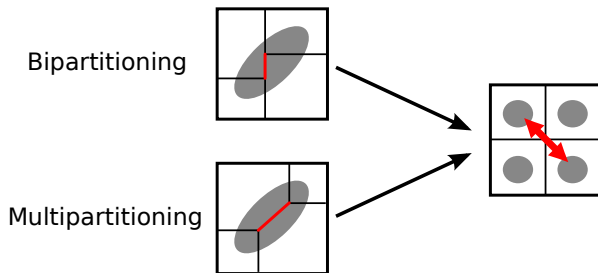
Results

Lookahead legalization

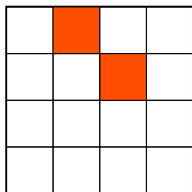
- ▶ Introduced by SimPL [2]

Lookahead legalization

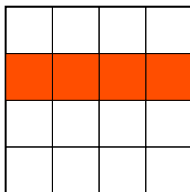
- ▶ Introduced by SimPL [2]
- ▶ Always based on partitioning



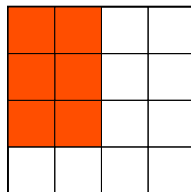
In Coloquinte: local optimizations



Two regions

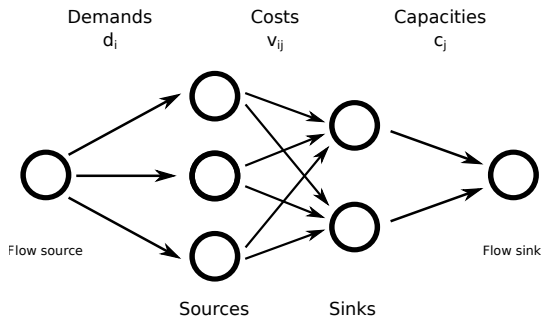


Row/Column

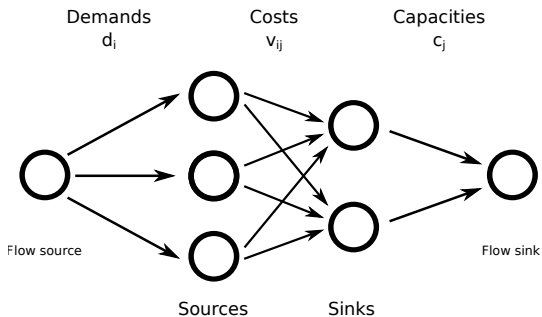


Multipartitioning

A transportation problem



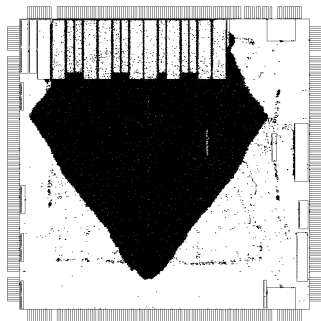
A transportation problem



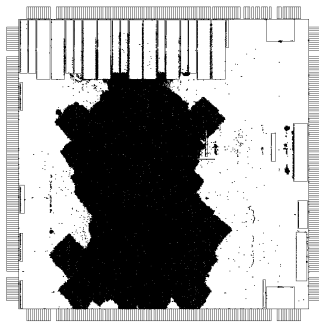
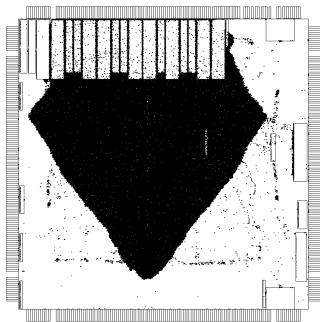
$\Omega(n^3)$ algorithms

Visual results

Visual results



Visual results

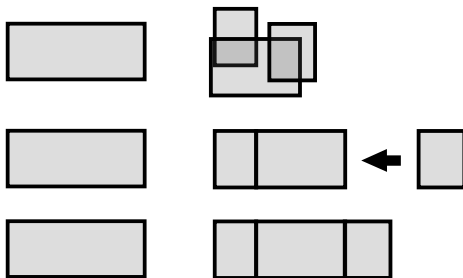


True legalization

Usually greedy

True legalization

Usually greedy

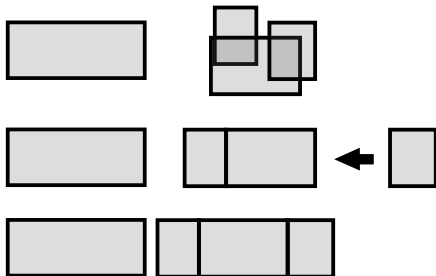


True legalization in Coloquinte

Push the previous cells [7]

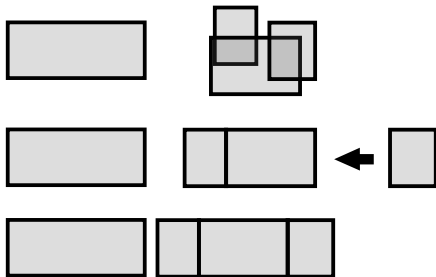
True legalization in Coloquinte

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True legalization in Coloquinte

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Even better: after a rough legalization

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Placement \approx scheduling

Machines \Leftrightarrow Rows

Tasks \Leftrightarrow Uniform-height cells

? \Leftrightarrow Wirelength

Our cost function is complicated

⇒ The cells are not independent

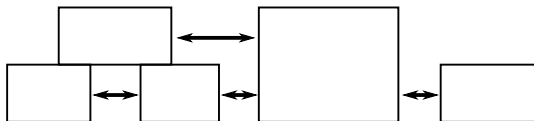
Our cost function is complicated

⇒ The cells are not independent

At fixed scheduling-order, dual of a *Minimum-cost flow problem*

Minimize $\sum \alpha_i x_i$

Subject to $x_{i_k} - x_{j_k} \leq d_k$



A simplified problem

Single row with fixed ordering

=

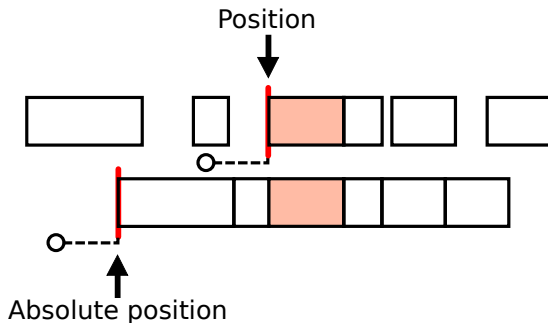
Single machine with fixed ordering

The cascading descent algorithm

Greedy algorithm with a single heap

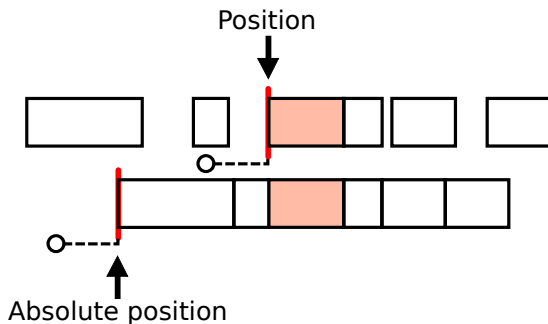
The cascading descent algorithm

Greedy algorithm with a single heap



The cascading descent algorithm

Greedy algorithm with a single heap



$O(n \log n)$ [4]

First use for placement

Everywhere in Coloquinte:

First use for placement

Everywhere in Coloquinte:

- ▶ Lookahead legalizer
- ▶ True legalizer
- ▶ Detailed placement reordering
- ▶ Whitespace allocation in detailed placement

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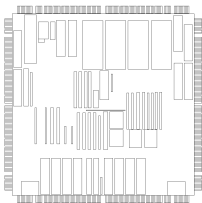
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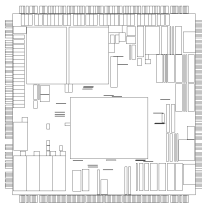
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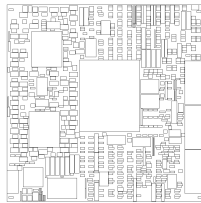
The ISPD05 benchmarks



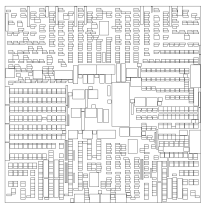
Adaptec1



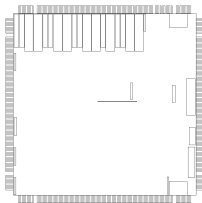
Adaptec2



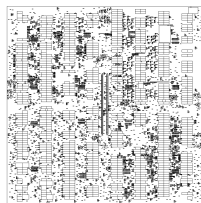
Adaptec3



Adaptec4

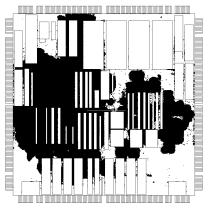


Bigblue1

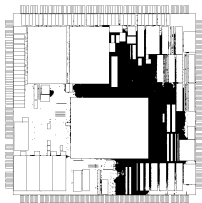


Bigblue2

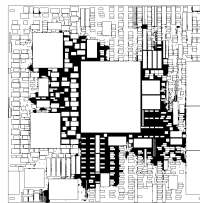
ISPD05 placements



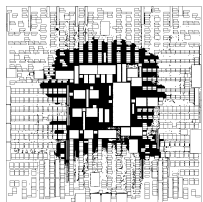
Adaptec1



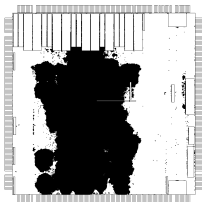
Adaptec2



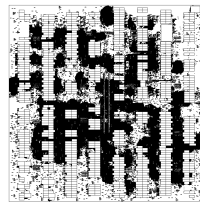
Adaptec3



Adaptec4



Bigblue1



Bigblue2

Not bad

Problem	ePlace	Best quadratic	Coloquinte	%
Adaptec1	74.63	76.36 (Maple)	76.49	+2.49
Adaptec2	84.84	86.16 (POLAR)	87.90	+3.61
Adaptec3	194.57	201.30 (POLAR)	202.12	+3.88
Adaptec4	179.02	179.91 (Maple)	182.27	+1.82
Bigblue1	90.99	93.74 (Maple)	94.76	+4.14
Bigblue2	141.83	143.95 (POLAR)	141.16	-0.47
Bigblue3	308.77	317.17 (Bonn)	#	#
Bigblue4	753.20	775.71 (Maple)	#	#

Quality comparison: HPWL (10^6 units)

Further work: placement

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- ▶ Switch to Nesterov optimization

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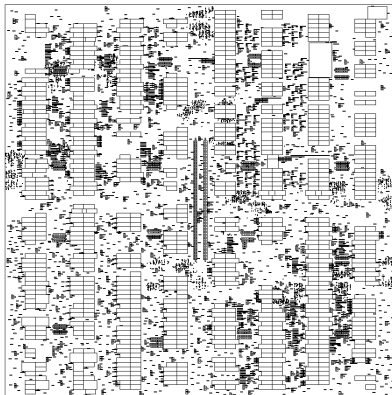
Further work: placement

- ▶ Switch to Nesterov optimization
- ▶ More legalization improvements
- ▶ Performance tuning
- ▶ Integer programming in detailed placement

Further work: routing, synthesis

- ▶ Gridless routing
- ▶ Specialized multiplier synthesis
- ▶ Placement-aware resynthesis

Questions



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